

SURFACE SUBSIDENCE MONITORING USING GPS TECHNOLOGY - RTK METHOD – AT LIVEZENI MINE

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Abstract

The Livezeni Mine is situated in eastern part of the Jiu Valley coal basin. The phenomenon of displacement and deformation of the surface land, continues to present a wide interest in the implications of environmental problems and protection of existing construction area. The researches in this direction have led to the conclusion that the observations made in the areas affected by underground mining can be done short-term forecasts, medium and long forecasts about the phenomenon analyzed. These forecasts have been particularly important in the sense that future studies can be made for sustainable development of areas affected by underground mining. Throughout

the duration of the existence of a mining the topography is an important component. Topogeodetic methods to study modern methods of tracking the movement of the land surface in the mining areas is a prerequisite for evidence the phenomenon in the future. The paper presents the method applied to monitor the surface subsidence at the Livezeni Mine.

1. Perimeter description of Livezeni Mine

The Livezeni Mine is situated in the eastern part of the Jiu Valley coal basin limited by the Petrila and Petrila Sud Mine's at north, Sălătruc Mine at south, Dâlja and Iscroni at west and Lonea Mine at east (fig. 1) [1].



Fig. 1. Jiu Valley Coal Basin

2. Surface subsidence monitoring in the case of Livezeni Mine using the RTK method

For surface subsidence monitoring using GPS technology – RTK method – on the general plan of the mine (figure 2), on which is flagged mined areas (longwall panels), have been designed the alignments after which we want to make measurements [7], [8].

So, four alignments have been designed, namely [8]:

- an transversal alignment $T_1 - T_1$ consisting of 24 benchmarks, the distance between them is

approximately 50m;

- three longitudinal alignments $L_{(3-4)} - L_{(3-4)}$, $L_5 - L_5$ and $L_6 - L_6$ located in the center of each panel. Those are composed of 20 benchmarks, the distance between them is also approximately 50m.

The coordinates of those benchmarks have been measured on the map and introduced in the GPS's memory (on the memory card).

Using the stakeout program (**09 Stakeout**) at the main measurement (the first measurement), which has been made at 15.09.2010, were stakeout all the points that forms the alignments, measuring at the same time their heights [6].

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The representation of land surface according to the distance between benchmarks, for each

alignment in part, is graphically presented in figures 3, 4, 5 and 6.

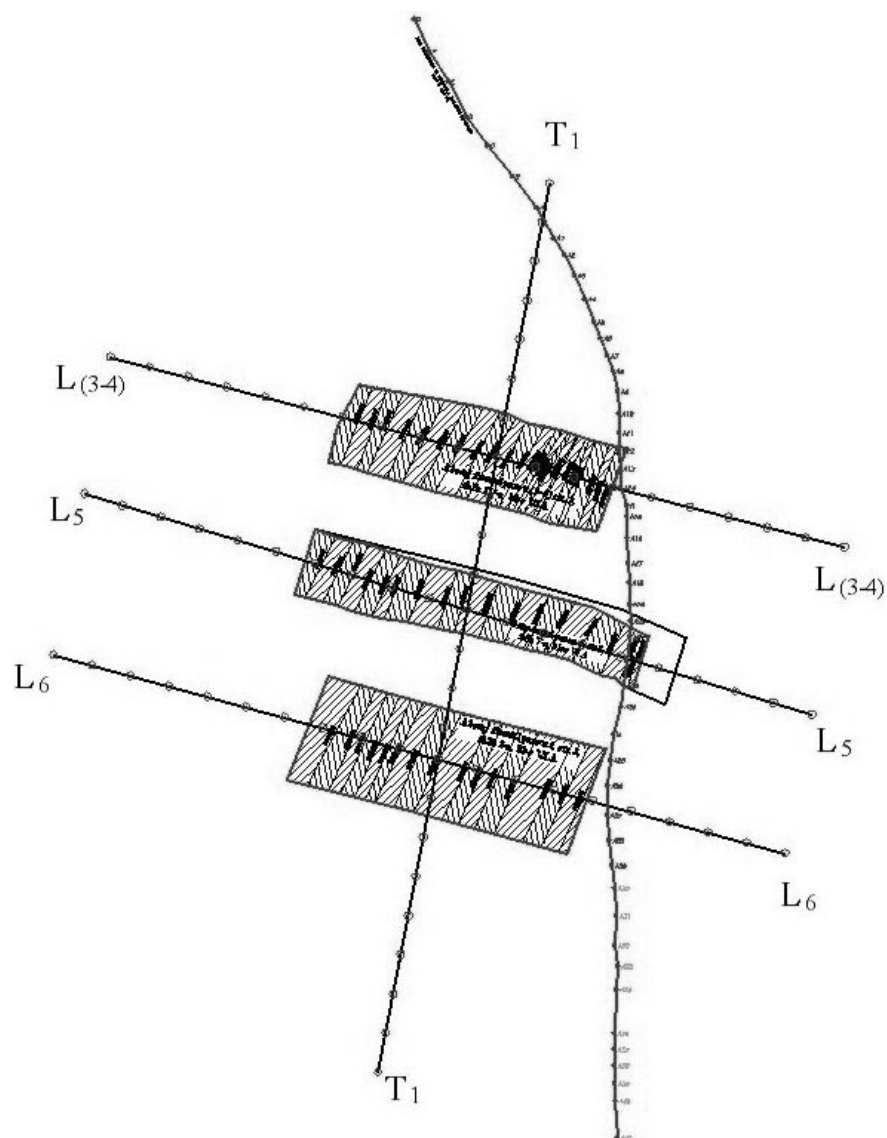


Fig. 2 Designed alignments for subsidence monitoring

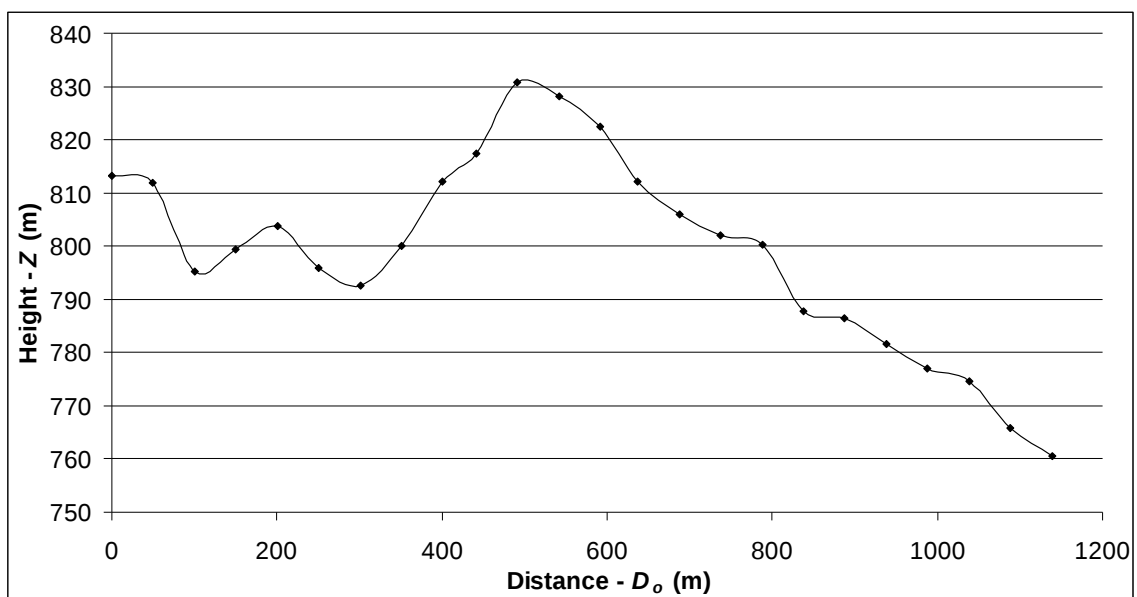


Fig. 3 Surface configuration in the transversal profile $T_1 - T_1$

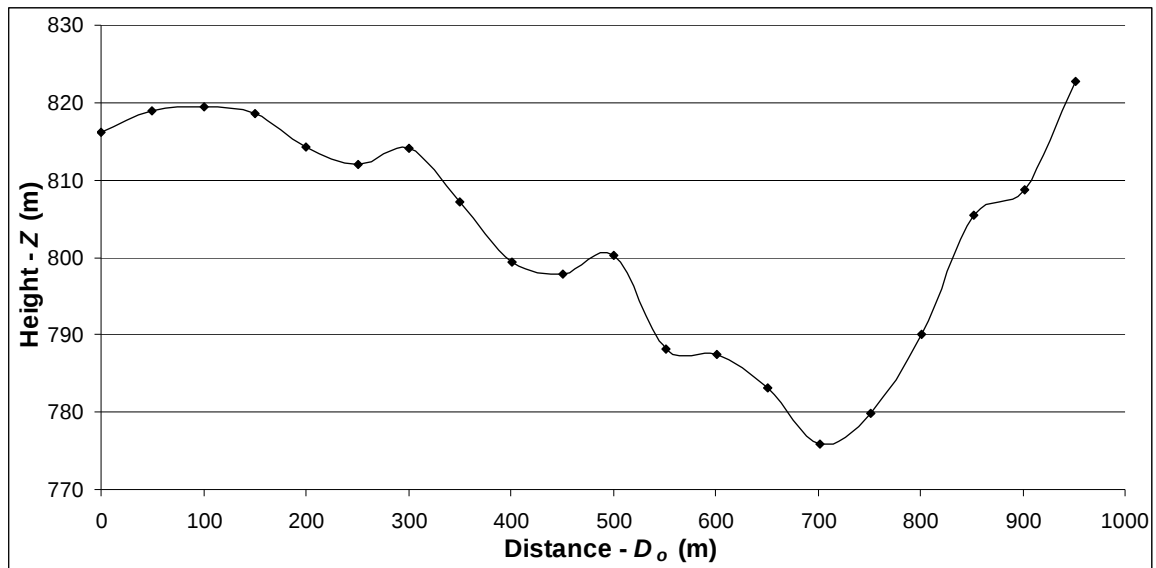


Fig. 4 Surface configuration in the longitudinal profile $L_{(3-4)} - L_{(3-4)}$

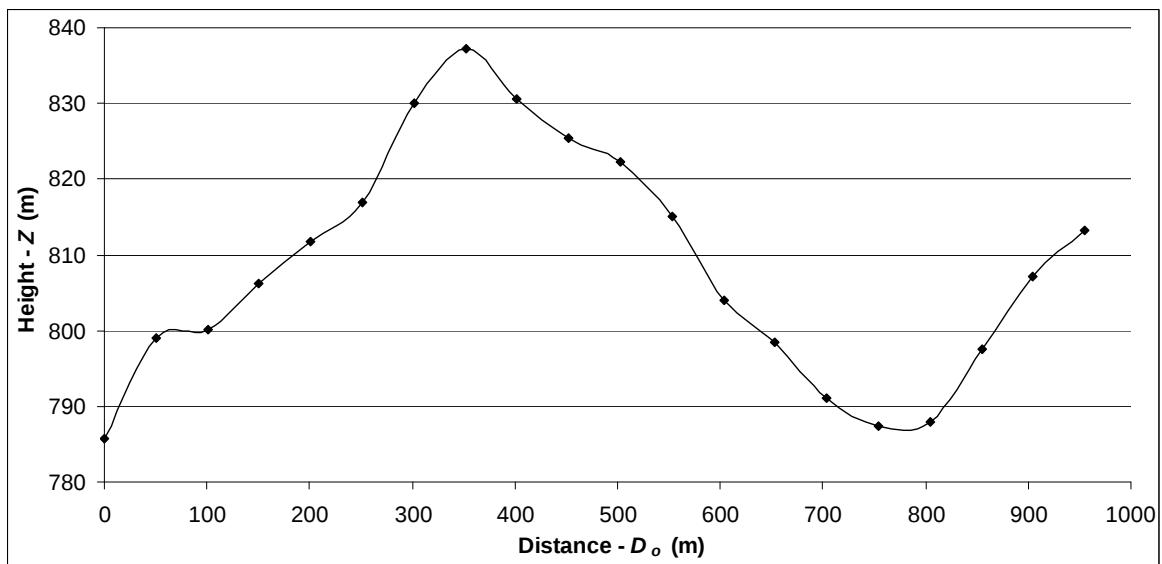


Fig. 5 Surface configuration in the longitudinal profile $L_5 - L_5$

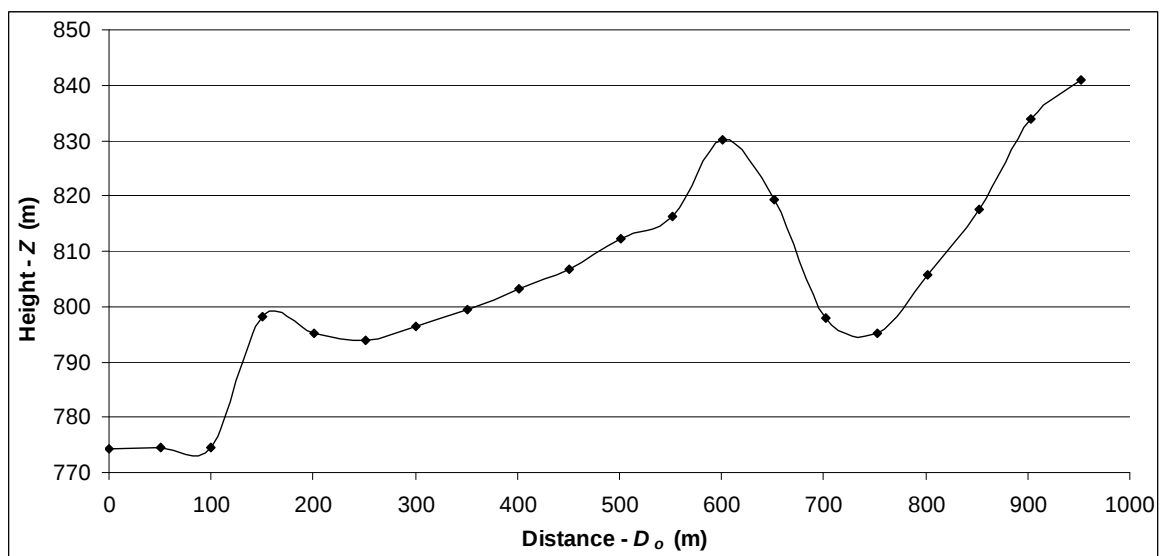


Fig. 6 Surface configuration in the longitudinal profile $L_6 - L_6$

In order to measure the surface movement, the second measurement was made after 6 months, on 19.03.2011 [8].

Using relation 1 the surface subsidence have been determined for each benchmark.

$$S_i = H_i^* - H_i \quad [mm] \quad (1)$$

In table 1 are presented the cumulated distance between benchmarks and their subsidence.

Table 1. Measured subsidence

Transversal alignment T₁ - T₁			Longitudinal alignment L₍₃₋₄₎ - L₍₃₋₄₎		
Benchmark	D (m)	S (mm)	Benchmark	D (m)	S (mm)
1	0,000	6	25	0,000	17
2	50,086	21	26	50,104	45
3	100,218	86	27	100,207	92
4	150,392	142	28	150,318	132
5	200,504	168	29	200,429	153
6	250,639	206	30	250,503	187
7	300,771	242	31	300,993	199
8	350,923	296	32	350,707	234
9	401,079	319	33	400,824	248
10	441,134	317	34	450,914	257
11	491,415	315	17	501,060	266
12	541,681	313	35	551,144	251
13	591,979	309	36	601,256	222
14	637,436	301	37	651,349	189
15	687,564	299	38	701,454	165
16	737,644	278	39	751,545	125
17	787,738	266	40	801,671	89
18	837,849	248	41	851,749	62
19	887,931	216	42	901,875	35
20	938,027	197	43	951,975	9
21	988,132	151			
22	1038,259	102			
23	1088,331	74			
24	1138,429	14			

Longitudinal alignment L₅ - L₅			Longitudinal alignment L₆ - L₆		
Benchmark	D (m)	S (mm)	Benchmark	D (m)	S (mm)
44	0,000	21	63	0,000	9
45	50,279	52	64	50,161	17
46	100,535	84	65	100,253	37
47	150,813	145	66	150,432	55
48	201,096	189	67	200,553	89
49	251,346	205	68	250,704	153
50	301,618	243	69	300,837	196
51	351,890	274	70	350,996	231
52	402,173	285	71	401,123	266
53	452,466	299	72	451,238	302
13	502,709	309	9	501,374	325
54	552,992	286	73	551,539	319
55	603,265	267	74	601,672	297
56	653,539	210	75	651,845	245
57	703,799	178	76	701,949	201
58	754,072	154	77	752,058	168
59	804,358	121	78	802,187	123
60	854,640	103	79	852,356	93
61	904,921	68	80	902,492	45
62	955,189	16	81	952,603	17

In figures 7 – 10 is represented the measured subsidence occurred to surface due to underground mining.

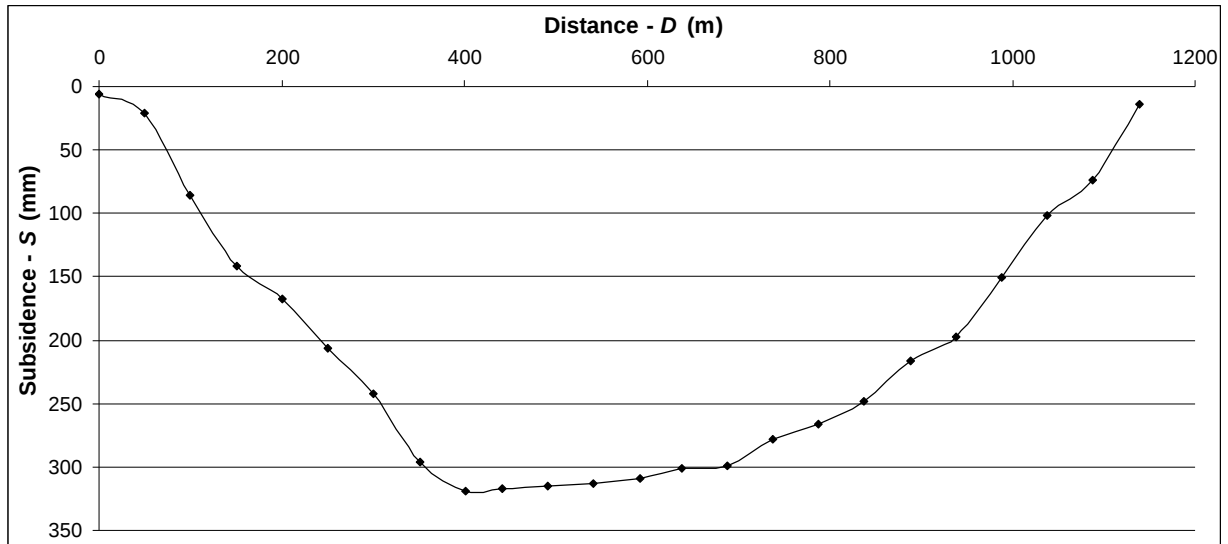


Fig. 7. Surface subsidence measured in the transversal profile $T_1 - T_1$

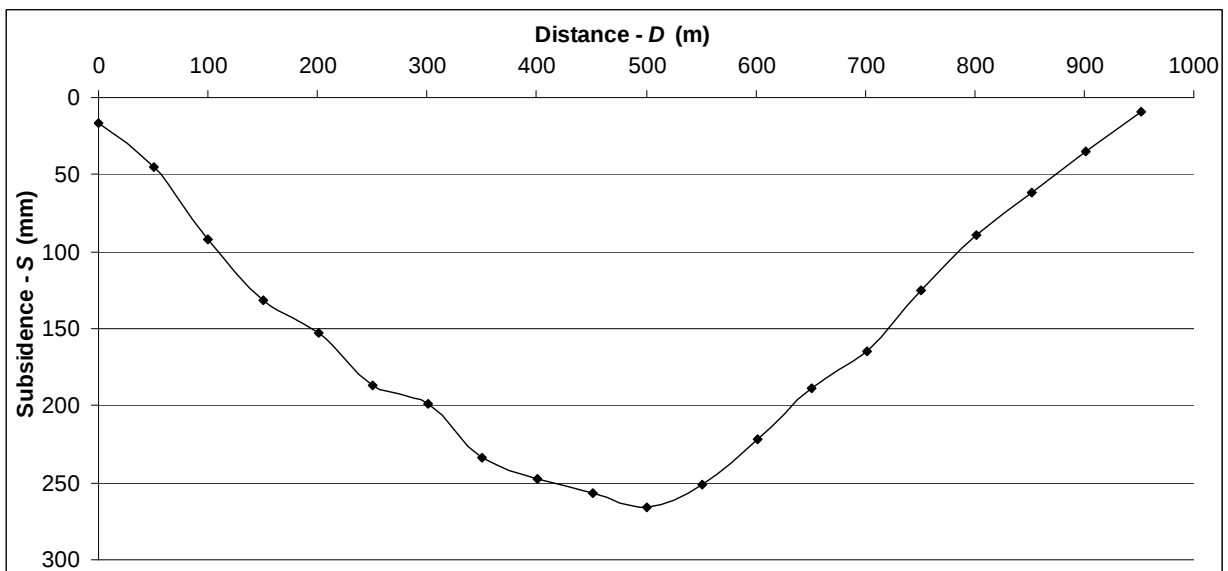


Fig. 8 Surface subsidence measured in the longitudinal profile $L_{(3-4)} - L_{(3-4)}$

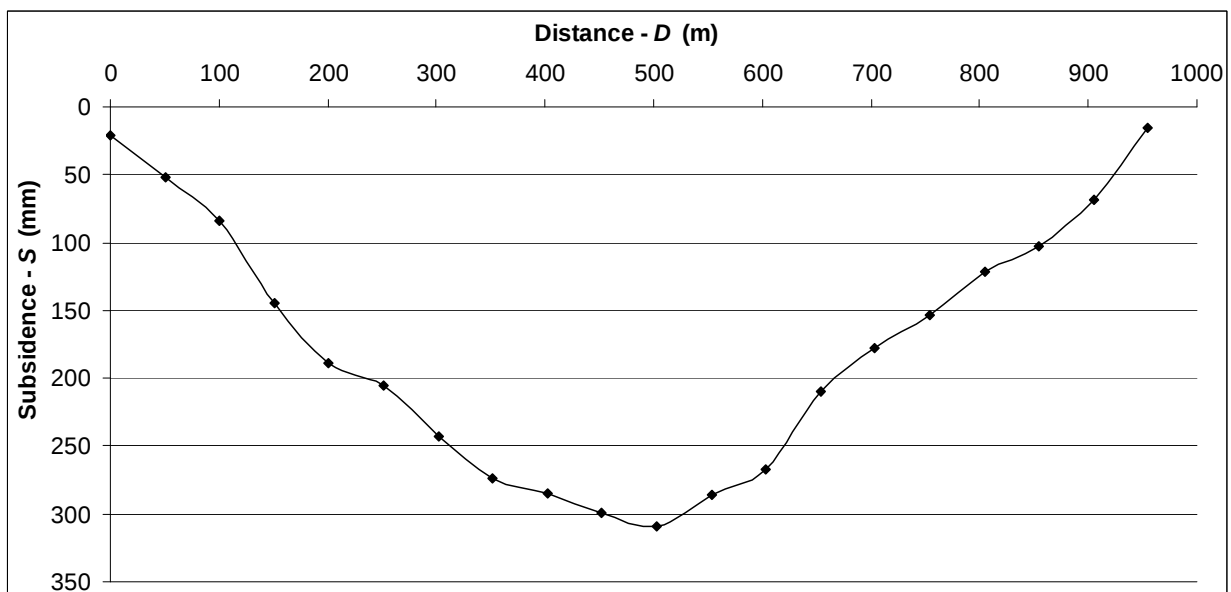


Fig. 9 Surface subsidence measured in the longitudinal profile $L_5 - L_5$

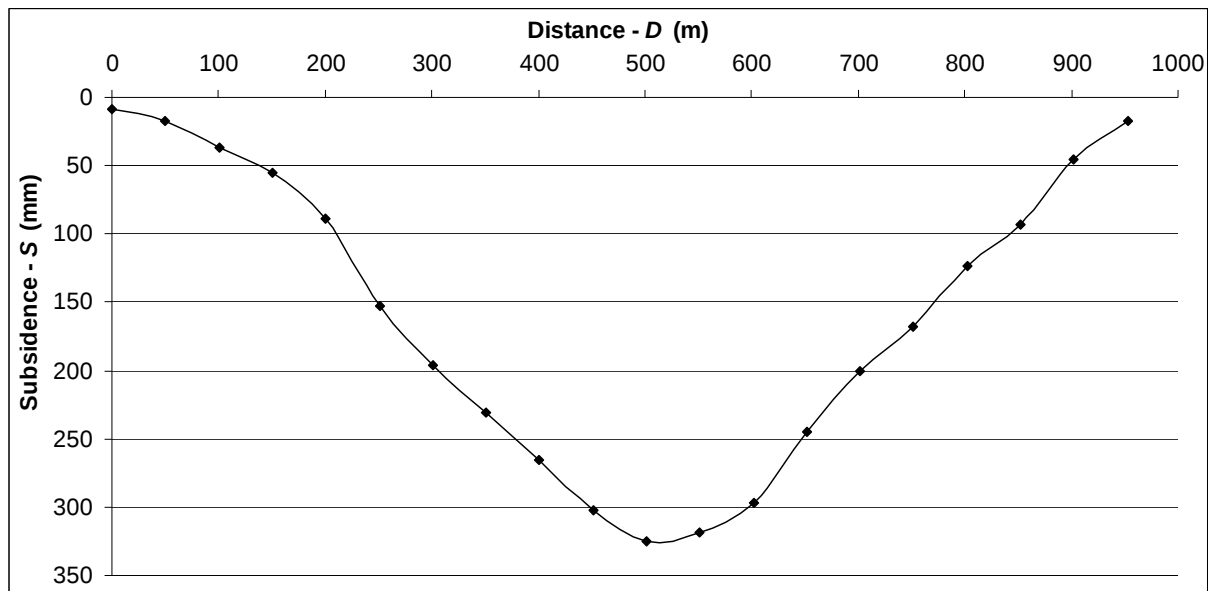


Fig. 10 Surface subsidence measured in the longitudinal profile $L_6 - L_6$

The statistical approximation of the measured subsidence, using the profile functions, will be shown bellow.

3. The statistical approximation of the measured subsidence at the Livezeni Mine

In 1981, Peng and Chen developed the following negative exponential function of the subsidence profile on the major cross section of the subsidence basin [2], [3], [4], [5]:

$$S(x) = S_{\max} \cdot A \quad (2)$$

where $A = e^{-a \cdot z^b}$; $S_{\max}$ is the maximum subsidence; a, b are constants; $z = \frac{x}{s}$; x is the horizontal distance

from the origin (which is located at the center of the subsidence profile); s is the half width of the subsidence basin [2], [3].

In order to obtain the complete subsidence profile, the relation (2) must be applied twice, for the left and right side of the subsidence profile, resulting different coefficients for each half of the subsidence profile: a_s, b_s and a_d, b_d .

Applying the relation of Peng and Chen in this way for the measured subsidence in the case of Livezeni Mine results [8]:

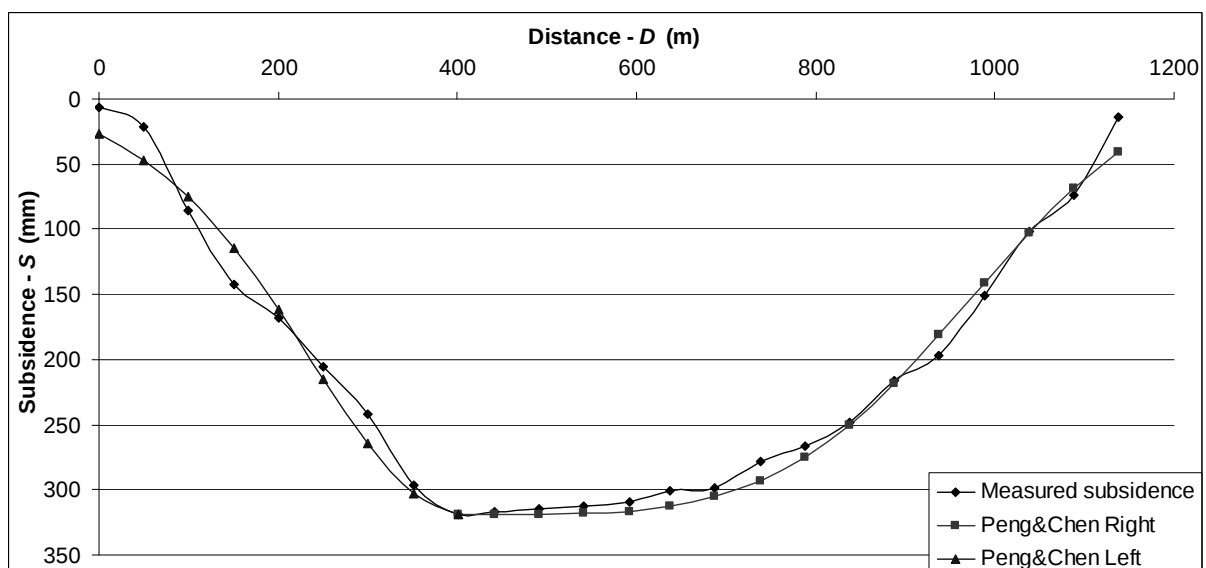


Fig. 11 Statistical approximation of the measured subsidence for the transversal profile $T_1 - T_1$

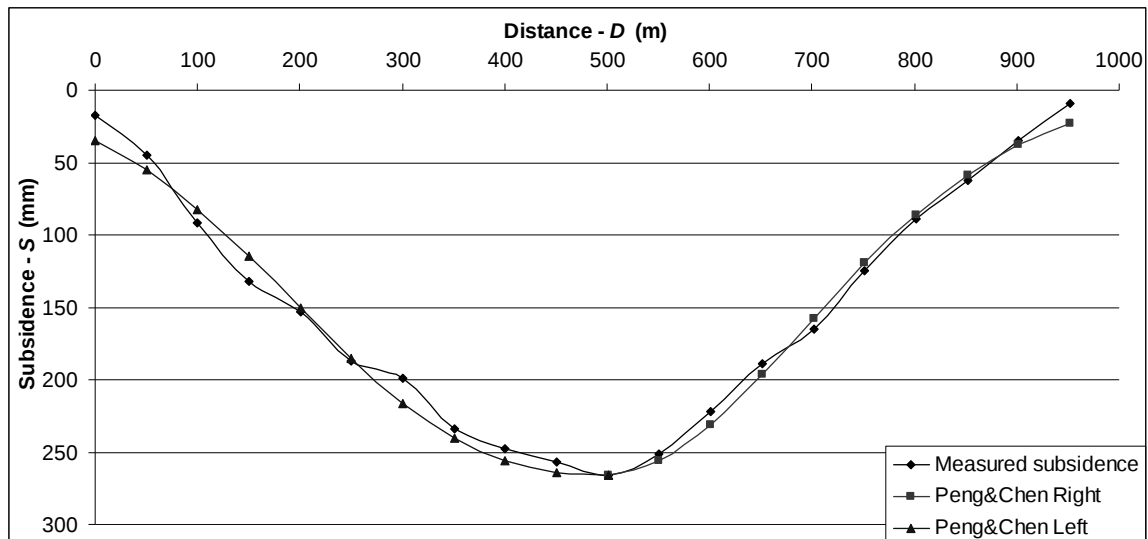


Fig.12 Statistical approximation of the measured subsidence for the longitudinal profile $L_{(3-4)}-L_{(3-4)}$

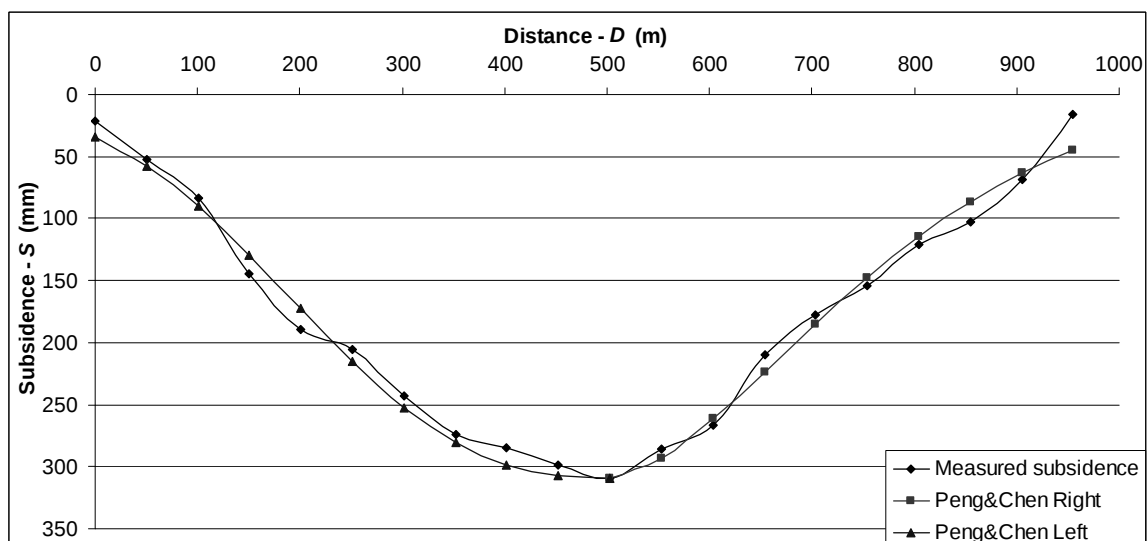


Fig. 13 Statistical approximation of the measured subsidence for the longitudinal profile $L_{(5)}-L_{(5)}$

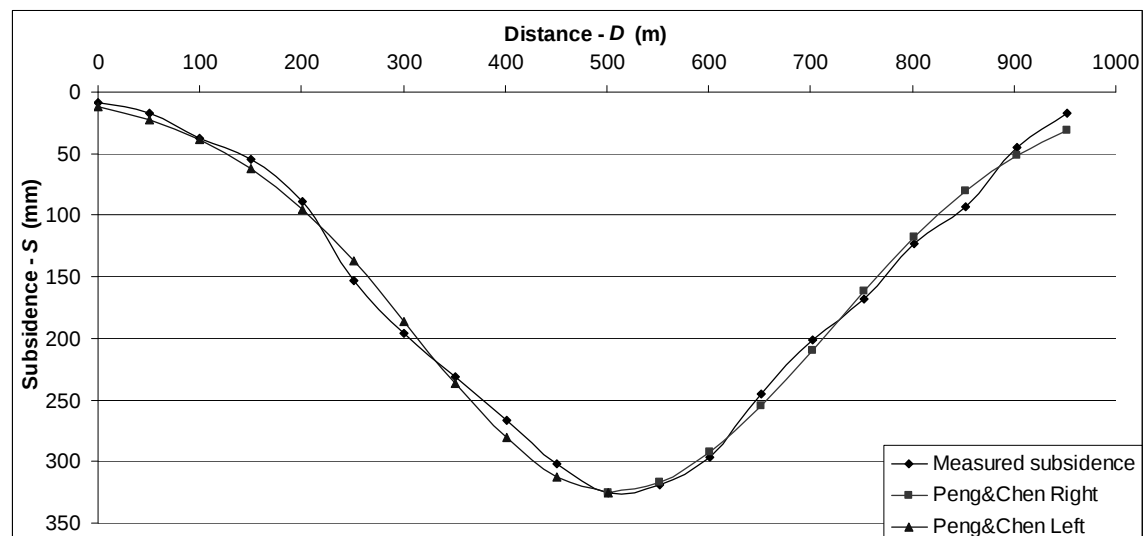


Fig. 14 Statistical approximation of the measured subsidence for the longitudinal profile $L_{(6)}-L_{(6)}$

As can be seen, the profile function developed by Peng and Chen approximates very well the measured subsidence. The coefficients obtained for

each half of the subsidence profile and the square of the coefficient of determination R^2 are presented in table 2.

Table 2

Alignment	Left part coefficients		Right part coefficients		Coefficient of determination	
	a_s	b_s	a_d	b_d	R_s^2	R_d^2
Transversal $T_1 - T_1$	2,466918	1,865147	0,243559	4,077078	0,992548	0,998375
Longitudinal $L_{(3-4)} - L_{(3-4)}$	2,039848	2,490492	2,437138	1,897701	0,996767	0,998286
Longitudinal $L_5 - L_5$	2,212215	2,605919	1,917403	1,624931	0,997625	0,995918
Longitudinal $L_6 - L_6$	3,303316	1,938924	2,346315	2,064628	0,997932	0,998539

4. Conclusions

In our case the surface subsidence monitoring at the Livezeni Mine is made on four alignments which are parallel with the direction of the seam respectively with his inclination.

In these alignments were performed two measurements (the basic measurement and a second measurement, performed after 6 months to capture the movement of land), using GPS technology, RTK method.

This method of monitoring the subsidence phenomenon can be easily applied in places where land topography permits. This method can also be applied using a total station but is a little more complicated.

Even if the RTK method is easy to apply, it presents some disadvantages including (perhaps most important are): high purchase price of this technology, a slightly lower accuracy than with conventional methods (leveling, etc.). Since by this method, the benchmarks which forms the alignments were not materialized, the horizontal displacement could not be determined.

In the present study, for the statistical approximation of the measurements at the Livezeni Mine (using the GPS technology - RTK method) has been used the profile function developed by Peng and Chen in 1981. This profile function can be applied only for half of the subsidence profile, starting from the maximum subsidence to zero. In our case this profile function was applied twice, for the left and right side of the subsidence profile. Applied in this way, for the approximation of the measurements made on the four alignments from the Livezeni Mine, the profile function developed by Peng and Chen led to the following results:

- for the transversal alignment $T_1 - T_1$ – the square of the coefficient of determination for each half of the subsidence profile are: $R_s^2 = 0,993$ and $R_d^2 = 0,998$;
- for the longitudinal alignment $L_{(3-4)} - L_{(3-4)}$ – the square of the coefficient of determination for each half of the subsidence profile are: $R_s^2 = 0,997$ and $R_d^2 = 0,998$;

- for the longitudinal alignment $L_5 - L_5$ – the square of the coefficient of determination for each half of the subsidence profile are: $R_s^2 = 0,998$ and $R_d^2 = 0,996$;

- for the longitudinal alignment $L_6 - L_6$ – the square of the coefficient of determination for each half of the subsidence profile are: $R_s^2 = 0,998$ and $R_d^2 = 0,999$;

Therefore the profile function developed by Peng and Chen gives very good results.

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Peer review: Prof.eng. Ph.D *Eugen Cozma*