Technical University of Cluj-Napoca Memorandumului 12, Cluj-Napoca, 400114 RO





# Levente TAMÁS

## Research interests

My research interests are related to the Al&robotics domain including map registration, localization, tracking, object detection and industrial applications.

## Education

2006–2009 **PhD**, Technical University of Cluj-Napoca.

supervisor Prof. dr. ing. Gheorghe LAZEA

description Sensor Fusion Based Mobile Robot Position Estimation

2000–2006 **BSc&MSc**, Technical University of Cluj-Napoca, final thesis at Ghent University.

honor Best academic results scholarship

# Work experience

2008-present Lecturer/Assoc. Prof./Prof., Technical University of Cluj-Napoca.

Giving robot control and pneumatic equipments courses for Control Engineering graduates

2020-present **Founder**, *Robotics&AI*.

Spin-off from TUCN - AI based services for robotics domain

2015–2017 **Postdoctoral Fellow**, *Pannon University*, Veszprem.

Change detection in multi-view camera setups

2013–2014 **Postdoctoral Fellow**, *BFH*, Bern.

3D Semantic Reconaissance

2010–2013 **Postdoctoral Fellow**, Technical University of Cluj-Napoca.

ArhiFax - Creating 3D maps in urban environments

2006–2007 Software Engineer, Evoline (Siemens partner), Cluj-Napoca.

Software design and development for Siemens TS department; SHTP team member

2005 **R&D Assistant**, *Solutia NV Europe*, Ghent.

Design and development of a new measurement system for thickness measurement

# Invited talks&Project PI

- 2022 AgroAI: R&D project in the agrobotics field, 150KEUR
- 2021 ToF based perception for mobile robots: Industrial project with NVidia, 250KEUR
- 2020 3D perception Al services: Industrial project with Analog Devices, 350KEUR
- 2018 ROS2AR: industrial project with NGI within H2020-ROSIN, 70KEUR
- 2017 3D perception made easy: Wokshop on 3D Image Processing, Veszprem, Hungary
- 2016 Active 3D perception: industrial project with Accentrure company, 100 KEUR
- 2015 3D pointcloud processing: COSCH Training School, Szeged, Hungary
- 2015 Relative pose estimation and fusion of 2D spectral and 3D lidar images: Computational Color Imaging Workshop, Saint Etienne, France
- 2014 Are we there yet? Towards autonomous driving challenges: International Summer Course on Multivariable Control: Automotive applications, Ghent, Belgium

## Academic activities and services

- 2020 Habilitation thesis defense
- 2018 HAS Bolyai scholarship award
- 2017 KEPAF Conference main organizer
- 2014 IEEE AQTR Conference WS organizer
- 2012 ROS fall school on cognitive systems, Munchen, participant
- 2011 Patenting OSIM patent no. A10006/16.02.2011
- 2010  $3^{rd}$  Intel ISIF student advisor award, 2010, USA
- 2009 Filtering and Data Analyses Summer School, Milan, participant
- 2008 SLAM Summer School, Sydney, participant
- 2007 National PhD research project director
- 2006 IEEE AQTR Conference organizer team member
- 2005 Erasmus exchange student at Ghent University, Belgium

## Skills

Languages Fluent spoken/written English, Hungarian and Romanian; fair German.

Programming C, C++, Matlab, Linux shell scripting, LATEX  $2_{\varepsilon}$ , Java, DeltaV.

#### Interests

Traveling, dancing, swimming.

## References

Available upon request